# 4xRealWebPhoto

**Dataset Preparation** 

# My own LUD-VAE model for realistic degradations

The goal here is to create a paired dataset with better realistic photo degradations and then train a photo model to evaluate how well it does. • S ●00 Ξ Ξ ユ \$\$ \$\$
U I zhengdharia/LUD-VAE: Official code for "Learn from Unpaired Data for Image Restoration: A Variational Bayes Approach" - Brave 📃 Upscale February 2024 - Go 🛛 😵 Selftrained | Helaman's Visi 😱 zhengdharia/LUD-VAE: 🗧 🗙 🕂 🖬 Q \prec | 🦁 🧷 🖷 ំ 🗖 🖻 = 📮 😘 github.com/zhengdharia/LUD-VAE | >\_ | [ + • ] 💿 🖪 🖾 🚮 zhengdharia / LUD-VAE <> Code ① Issues 2 11 Pull requests ④ Actions 🕀 Projects ③ Security 🗠 Insights 🕕 LUD-VAE (Public ¥ main → ¥ 1 Branch ⊙ 0 Tags <> Code + About Official code for "Learn from Unpaired n zhengdharia Update README.md Data for Image Restoration: A Variational Bayes Approach" LUD\_VAE\_aim19 🗂 Readme LUD\_VAE\_dnd δ∱δ MIT license LUD\_VAE\_lol ☆ 11 stars LUD\_VAE\_ntire20 1 watching LUD\_VAE\_sidd □ LICENSE □ README.md Releases □ README AT MIT license Packages LUD-VAE Languages Official code for our paper "Learn from Unpaired Data for Image Restoration: A Variational Bayes Approach". Python 99.7% MATLAB 0.3% **Dataset Preparation** For AIM19 and NTIRE20, the dataset preparation is the same with the DeFlow method. See For SIDD, we use the SIDD-Small Dataset, which can be download from https://www.eecs.yorku.ca/~kamel/sidd/dataset.php. We crop the images in SIDD-Small dataset to 512x512x3 patches.



📌 TODO































**Create effective** multimedia presentations





















0.062 0.000 -0.062 0.005 | 0.000 | 24-02-20 22:41:55.192 : <epoch: 83, iter: 91,000, lr:1.000e-04> loss: 2.136e-04 reconstruction loss: 2.136e-04 kl loss: 0.000e+00 24-02-20 22:47:23.235 : <epoch:166, iter: 92,000, lr:1.000e-04> loss: 2.108e-04 reconstruction loss: 2.108e-04 kl loss: 0.000e+00 24-02-20 22:52:48.950 : <epoch:249, iter: 93,000, lr:1.000e-04> loss: 2.081e-04 reconstruction\_loss: 2.081e-04 kl\_loss: 0.000e+06 24-02-20 22:58:14.766 : <epoch:333, iter: 94,000, lr:1.000e-04> loss: 2.049e-04 reconstruction loss: 2.049e-04 kl loss: 0.000e+00 24-02-20 23:03:40.196 : <epoch:416, iter: 95,000, lr:1.000e-04> loss: 1.718e-04 reconstruction loss: 1.718e-04 kl loss: 0.000e+00 24-02-20 23:09:05.892 : <epoch:499, iter: 96,000, lr:1.000e-04> loss: 1.669e-04 reconstruction loss: 1.669e-04 kl loss: 0.000e+00 24-02-20 23:14:31.652 : <epoch:583, iter: 97,000, lr:1.000e-04> loss: 1.593e-04 reconstruction loss: 1.593e-04 kl loss: 0.000e+06 24-02-20 23:19:57.196 : <epoch:666, iter: 98,000, lr:1.000e-04> loss: 2.438e-04 reconstruction loss: 2.438e-04 kl loss: 0.000e+00 24-02-20 23:25:22.894 : <epoch:749, iter: 99,000, lr:1.000e-04> loss: 2.700e-04 reconstruction loss: 2.700e-04 kl loss: 0.000e+00 24-02-20 23:30:48.747 : <epoch:833, iter: 100,000, lr:2.500e-05> loss: 2.155e-04 reconstruction loss: 2.155e-04 kl loss: 0.000e+00 24-02-20 23:30:48.747 : Saving the model. 24-02-20 23:36:14.970 : <epoch:916, iter: 101,000, lr:5.000e-05> loss: 2.003e-04 reconstruction loss: 2.003e-04 kl loss: 0.000e+00 24-02-20 23:41:40.953 : <epoch:999, iter: 102,000, lr:5.000e-05> loss: 1.787e-04 reconstruction loss: 1.787e-04 kl loss: 0.000e+00 24-02-20 23:47:07.072 : <epoch:1083, iter: 103.000, lr:5.000e-05> loss: 1.924e-04 reconstruction loss: 1.924e-04 kl loss: 0.000e+00 24-02-20 23:52:33.057 : <epoch:1166, iter: 104,000, lr:5.000e-05> loss: 1.581e-04 reconstruction loss: 1.581e-04 kl loss: 0.000e+00 24-02-20 23:57:59.038 : <epoch:1249, iter: 105,000, lr:5.000e-05> loss: 2.214e-04 reconstruction loss: 2.214e-04 kl loss: 0.000e+00 24-02-21 00:03:24.934 : <epoch:1333, iter: 106,000, lr:5.000e-05> loss: 1.975e-04 reconstruction loss: 1.975e-04 kl loss: 0.000e+00 24-02-21 00:08:50.814 : <epoch:1416, iter: 107,000, lr:5,000e-05> loss: 1,924e-04 reconstruction loss: 1,924e-04 kl loss: 0,000e+00 24-02-21 00:14:16.745 : <epoch:1499, iter: 108,000, lr:5.000e-05> loss: 2.096e-04 reconstruction loss: 2.096e-04 kl loss: 0.000e+00 24-02-21 00:25:08.836 : <epoch:1666, iter: 110,000, lr:5.000e-05> loss: 2.361e-04 reconstruction loss: 2.361e-04 kl loss: 0.000e+00 24-02-21 00:25:08.836 : Saving the model. 24-02-21 00:30:34.885 : <epoch:1749, iter: 111,000, lr:5.000e-05> loss: 1.918e-04 reconstruction loss: 1.918e-04 kl loss: 0.000e+00 24-02-21 00:36:00.778 : <epoch:1833, iter: 112,000, lr:5.000e-05> loss: 2.590e-04 reconstruction loss: 2.590e-04 kl loss: 0.000e+00 24-02-21 00:41:26.775 : <epoch:1916, iter: 113,000, lr:5.000e-05> loss: 1.929e-04 reconstruction loss: 1.929e-04 kl loss: 0.000e+00 24-02-21 00:46:52.588 : <epoch:1999, iter: 114,000, lr:5.000e-05> loss: 1.617e-04 reconstruction loss: 1.617e-04 kl loss: 0.000e+00 24-02-21 00:52:18.664 : <epoch:2003, iter: 115,000, lr:5.000e-05> loss: 2.019e-04 reconstruction loss: 2.019e-04 kl loss: 0.000e+00 24-02-21 00:57:44.596 : <epoch:2166, iter: 116,000, lr:5.000e-05> loss: 2.224e-04 reconstruction loss: 2.224e-04 kl loss: 0.000e+00 24-02-21 01:03:10.293 : <epoch:2249, iter: 117,000, lr:5.000e-05> loss: 2.079e-04 reconstruction loss: 2.079e-04 kl loss: 0.000e+00 24-02-21 01:08:36.259 : <epoch:2333, iter: 118,000, lr:5.000e-05> loss: 1.794e-04 reconstruction loss: 1.794e-04 kl loss: 0.000e+00 24-02-21 01:19:27.851 : <epoch:2499, iter: 120,000, lr:5.000e-05> loss: 2.137e-04 reconstruction loss: 2.137e-04 kl loss: 0.000e+00 24-02-21 01:19:27.851 : Saving the model 24-02-21 01:30:20.100 : <epoch:2666, iter: 122,000, lr:5.000e-05> loss: 1.943e-04 reconstruction loss: 1.943e-04 kl loss: 0.000e+00 24-02-21 01:35:46.045 : <epoch:2749, iter: 123,000, lr:5.000e-05> loss: 1.956e-04 reconstruction loss: 1.956e-04 kl loss: 0.000e+00 24-02-21 01:41:12.123 : <epoch:2833, iter: 124,000, lr:5.000e-05> loss: 1.664e-04 reconstruction loss: 1.664e-04 kl loss: 0.000e+00 24-02-21 01:46:37.944 : <epoch:2916, iter: 125,000, lr:5.000e-05> loss: 2.182e-04 reconstruction loss: 2.182e-04 kl loss: 0.000e+00 24-02-21 01:52:03.995 : <epoch:2999, iter: 126,000, lr:5.000e-05> loss: 2.016e-04 reconstruction loss: 2.016e-04 kl loss: 0.000e+00 24-02-21 01:57:29.984 ; <epoch:3083, iter: 127.000, lr:5.000e-05> loss: 1.962e-04 reconstruction loss: 1.962e-04 kl loss: 0.000e+00 24-02-21 02:02:55.935 : <epoch:3166, iter: 128,000, lr:5.000e-05> loss: 1.891e-04 reconstruction loss: 1.891e-04 kl loss: 0.000e+00 24-02-21 02:08:21.774 : <epoch:3249, iter: 129,000, lr:5.000e-05> loss: 1.874e-04 reconstruction loss: 1.874e-04 kl loss: 0.000e+00 24-02-21 02:13:47.869 : <epoch:3333, iter: 130,000, lr:5.000e-05> loss: 1.851e-04 reconstruction loss: 1.851e-04 kl loss: 0.000e+00 24-02-21 02:13:47.869 : Saving the model. 24-02-21 02:19:13.724 : <epoch:3416, iter: 131,000, lr:5.000e-05> loss: 1.649e-04 reconstruction loss: 1.649e-04 kl loss: 0.000e+00 24-02-21 02:24:39.884 : <epoch:3499, iter: 132,000, lr:5.000e-05> loss: 2.219e-04 reconstruction loss: 2.219e-04 kl loss: 0.000e+00 24-02-21 02:30:06.182 : <epoch:3583, iter: 133,000, lr:5.000e-05> loss: 2.081e-04 reconstruction loss: 2.081e-04 kl loss: 0.000e+00 24-02-21 02:35:32.167 : <epoch:3666, iter: 134,000, lr:5.000e-05> loss: 2.379e-04 reconstruction loss: 2.379e-04 kl loss: 0.000e+00 24-02-21 02:40:58.110 : <epoch:3749, iter: 135,000, lr:5.000e-05> loss: 2.044e-04 reconstruction loss: 2.044e-04 kl loss: 0.000e+00 24-02-21 02:46:24.362 : <epoch:3833, iter: 136,000, lr:5.000e-05> loss: 2.290e-04 reconstruction loss: 2.290e-04 kl\_loss: 0.000e+06 24-02-21 02:51:50.340 : <epoch:3916, iter: 137,000, lr:5.000e-05> loss: 2.270e-04 reconstruction loss: 2.270e-04 kl loss: 0.000e+00 24-02-21 02:57:16.330 : <epoch: 3999, iter: 138,000, lr:5.000e-05> loss: 1.800e-04 reconstruction loss: 1.800e-04 kl loss: 0.000e+00 24-02-21 03:02:42.422 : <epoch:4083, iter: 139,000, lr:5.000e-05> loss: 2.069e-04 reconstruction loss: 2.069e-04 kl loss: 0.000e+00

# 2 nights, ~ 17 hours, 190'000 iters



Example: Realistic noise added with my own degradation models

# Gameplan: 4xRealWebPhoto Paired Dataset

Simulating usecase:

Someone taking a photo (with a bit of noise and blur in it), then uploads it on the web (social media / travel blog / website etc) where the service automatically downscaled and compresses the image for web usage.

Then another Person liking the photo, downloading it, and re-uploading it on the web (where provider automatically scales and compresses for web usage again).

So here we create a paired 4x Dataset and simulate these degradations by taking a photography training dataset and then:

Applying realistic (lens) blur

Applying realistic noise

Downsample to half and then jpg compress. Here we are using multiple downsampling algorithms at random, and also randomized jpg compression between 60-100 (google search image preview would be at around 70, so this would also catch the case of someone downloading the google preview image of a good quality photo). I use multiple downsampling algorithms and a compression range since I do not know what default values a service provider would use so we just handle them all.

Re-downsampling and re-compressing again (so previous step again). Now the Ir's will be at quarter size for 4x paired training dataset and we have simulated the use case of downloading and upscaling a photo from the web.



Photo, little bit of blur and noise



Web Service scales and compresses



Some user downloads the image



Some other User downloads image, wants to upscale



Web Service scales and compresses

RSBlur

## Realistic Blur Synthesis for Learning Image Deblurring



### Realistic Blur Synthesis for Learning Image Deblurring

Jaesung Rim, Geonung Kim, Jungeon Kim, Junyong Lee, Seungyong Lee, Sunghyun Cho



Example images from the RSBlur Dataset after I finished degrading them - more infos in the appendix on this process

2024-02-22 20:00:25.352 INFO: ----- neosr Pvtorch Version: 2.2.0.dev20230914+cu121 2024-02-22 20:00:35,285 INFO: Dataset [paired] 2024-02-22 20:00:35,285 INFO: Training statist Starting model: 4xRealSISR\_rgt\_s Number of train images: 1175 Dataset enlarge ratio: 5 Batch size per gpu: 12 World size (gpu number): 1 Required iters per epoch: 490 Total epochs: 1021: iters: 500000. 2024-02-22 20:00:35,285 INFO: Dataset [paired] 2024-02-22 20:00:35,286 INFO: Number of val in 2024-02-22 20:00:36,327 INFO: Network [rgt] is 2024-02-22 20:00:36,421 INFO: Network [unet] i 2024-02-22 20:00:38,597 INFO: Loading rgt mode [params]. 2024-02-22 20:00:38,748 INFO: Loss [HuberLoss] 2024-02-22 20:00:39,080 INFO: Loss [Perceptua] 2024-02-22 20:00:39,081 INFO: Loss [GANLoss] : 2024-02-22 20:00:39,081 INFO: Loss [colorloss] 2024-02-22 20:00:39,089 INFO: Model [default] is created. 2024-02-22 20:00:39,949 INFO: Using CUDA prefetch dataloader. 2024-02-22 20:00:39,949 INFO: AMP enabled. 2024-02-22 20:00:39,949 INFO: Start training from epoch: 0, iter: 0 2024-02-22 20:49:41,478 INFO: [epoch: 10] [iter: 5,000] [performance: 1.697 it/s] [lr:(7.143e-05)] [eta: 3 days, 8:34:57, data\_time: 3.5581e-03 l\_g\_pix: 3.1343e-03 l\_percep: 6.0649e+00 l\_g\_color: 9.3354e-04 l\_g\_gan: 8.8242e-02 l\_d\_real: 9.6620e-01 out\_d\_real: -4.4727e-01 l\_d\_fake: 5.6470e-01 out\_d\_fake: -3.1836e-01 2024-02-22 20:49:41,478 INFO: Saving models and training states. 2024-02-22 20:50:01,904 INFO: Validation val # psnr: 22,9585 Best: 22,9585 @ 5000 iter # ssim: 0.3594 Best: 0.3594 @ 5000 iter

2024-02-22 21:38:55,121 INFO: [epoch: 20] [iter: 10,000] [performance: 1.711 it/s] [lr:(1.429e-04)] [eta: 3 days, 8:05:11, data\_time: 2.0218e-04 l\_g\_pix: 1.1371e-03 l\_percep: 5.5915e+00 l\_g\_color: 2.2461e-04 l\_g\_gan: 6.8779e-02 l\_d\_real: 6.5932e-01 out\_d\_real: 7.2754e-02 l\_d\_fake: 7.0201e-01 out\_d\_fake: 1.4099e-02 2024-02-22 21:38:55,122 INFO: Saving models and training states. 2024-02-22 21:39:13,559 INFO: Validation val # psnr: 27.4585 Best: 27.4585 @ 10000 iter

# ssim: 0.5913 Best: 0.5913 @ 10000 iter

2024-02-22 22:28:03,629 INF0: [epoch: 30] [iter: 15,000] [performance: 1.707 it/s] [lr:(2.143e-04)] [eta: 3 days, 7:19:41, data\_time: 2.1109e-04 l\_g\_pix: 1.3216e-03 l\_percep: 5.0609e+00 l\_g\_color: 2.0179e-04 l\_g\_gan: 9.0105e-02 l\_d\_real: 5.7890e-01 out\_d\_real: 1.2422e+00 l\_d\_fake: 6.7330e-01 out\_d\_fake: -2.2949e-01 2024-02-22 22:28:03,630 INF0: Saving models and training states. 2024-02-22 22:28:22,132 INF0: Validation val

Trained 2 experiment models with it, compact for 40k and rgt\_s for 70k. Degrdataions / Motion blur in dataset is too strong. Better: Find a method to degrade with realistic blur with adjustable strengths instead of using pre-blurred dataset I cannot adjust

### **Blur Generator**

python 3.6   3.7	3.8   3.9   3.10	3.11 imp	plementation	cpytho
() Test passing (	) Release passin	9		
status stable licer	nse MIT			
pypi package 1.0.	4			
downloads 436/mc	onth downloads	49/week	downloads	9/day
MADE WITH	РҮТНОМ	•		

This tool is for generating blur on images.

There are 3 types of blur modes of motion , lens , or gaussian .

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	24				
nomos8k_	0072.png	0150.png	0150_lens_	0150_lens_	0150_lens_
sfw			r1_c4_e2.	r2_c2_e3.	r2_c2_e4.
			png	png	png
0150_lens_	0150_lens_	0150_lens_	0150_lens_	0150_lens_	0150_lens_
r2_c3_e2.	r2_c4_e2.	r2_c5_e4.	r2_c6_e4.	r3_c4_e2.	r4_c4_e1.
png	png	png	png	png	png
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0150_lens_	0150_lens_	blur.py			
ro_c4_e2.	r7_c4_e2.				
prig	Prig				
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os@phips-MS-7C0					
phips@phips-	MS-7C02:~/Doo	cuments/datas	ets/RealSISE	v2\$ pvthon	blur.pv
phips@phips-	MS-7C02:~/Doc	cuments/datas	ets/RealSISF	_v2\$	

from blurgenerator import lens\_blur

mport cv2

img = cv2.imread('0150.png')
result = lens\_blur(img, radius=1, components=4, exposure\_gamma=2)
cv2.imwrite('./0150\_lens\_r1\_c4\_e2.png', result)

img = cv2.imread('0150.png')
result = lens\_blur(img, radius=2, components=4, exposure\_gamma=2)
cv2.imwrite('./0150\_lens\_r2\_c4\_e2.png', result)

img = cv2.imread('0150.png')
result = lens\_blur(img, radius=3, components=4, exposure\_gamma=2)
cv2.imwrite('./0150\_lens\_r3\_c4\_e2.png', result)

6 img = cv2.imread('0150.png') 7 result = lens\_blur(img, radius=4, components=4, exposure\_gamma=2) 8 cv2.imwrite('./0150\_lens\_r4\_c4\_e1.png', result)

img = cv2.imread('0150.png')
result = lens\_blur(img, radius=5, components=4, exposure\_gamma=2)
cv2.imwrite('./0150\_lens\_r5\_c4\_e2.png', result)

img = cv2.imread('0150.png')
result = lens\_blurdimg, radius=6, components=4, exposure\_gamma=2
cv2.imwrite('./0150\_lens\_r6\_c4\_e2.png', result)

Bimg = cv2.imread('0150.png')
Presult = lens\_blur(img, radius=7, components=4, exposure\_gamma=2)
Cv2.imwrite('./0150\_lens\_r7\_c4\_e2.png', result)

img = cv2.imread('0150.png')
result = lens\_blur(img, radius=2, components=4, exposure\_gamma=2)
cv2.imwrite('./0150\_lens\_r2\_c4\_e2.png', result)

0 img = cv2.imread('0150.png')
1 result = lens\_blur(img, radius=2, components=5, exposure\_gamma=2)
2 cv2.imwrite('./0150\_lens\_r2\_c5\_e4.png', result)

img = cv2.imread('0150.png')
result = lens\_blur(img, radius=2, components=6, exposure\_gamma=2)
cv2.imwrite('./0150\_lens\_r2\_c2\_e4.png', result)

simg = cv2.imread('0150.png')
result = lens\_blur(img, radius=2, components=2, exposure\_gamma=2)

Testing out lens blurs / strengths



Testing strengths visualization lens blur

So after testing and what I learned from last dataset try, I now have a complete degradation pipeline.

This time, I took the nomos8k\_sfw dataset from musl, which is a photo dataset.

It has good variety, consists of 6118 images of 512x512 px.

Since its 512x512 I will be able to apply realistic blur, then realistic noise (no out of vram), then downscale+jpg, downscale+jpg like previously.

(and its sfw so I can show here)



Example images nomos8k\_sfw

ips@phips-ins-7C02:~/Documents/datasets/RealstsR_V2	Ch	🔹 degra	de_with_lens_blur.py 1 🗙		
2365.png - Iens blur radius: 2		home \ phine \ Decuments \ detects \ DeclETED v0 \ + describe with lens bluenv \			
1371.png - lens blur radius: 2		nome / philps / Documents / datasets / kealstas_v2 / 👻 degrade_with_tens_bidupy /			
1027.png – lens blur radius: 2	$\mathcal{Q}$	29 def print_text_to_textfile(file_name, text_to_append):			
5453.png - lens blur radius: 2			file object.write(text to append)		
1279.png - lens blur radius: 1	0				
6408.png - lens blur radius: 3	Re Po	41			
5655.png - lens blur radius: 3		42	# iterate over files in folder		
1639.png - lens blur radius: 1		43	for filename in os listdir(input folder nath):		
4507.png - lens blur radius: 3	æ^		Tendre Institutupat_locaepath/.		
3278.png - lens blur radius: 1		44.			
0009.png - lens blur radius: 2	00		# check 11 Image		
4263.png - lens blur radius: 3			1T TILENAME.endSwith('.png'):		
5869.png - lens blur radius: 1		47			
3727.png - lens blur radius: 1	Д		# construct full input file path		
0409 ppg - lens blur radius: 1			input_file_path = os.path.join(input_folder_path, filename)		
0431 ppg - lens blur radius: 3					
2607 ppg - lens blur radius: 2		51	# read the image using cv2		
5836 nng - lens blur radius: 1		52	<pre>img = cv2.imread(input file path)</pre>		
4950 ppg - lens blur radius: 1					
6410 ppg - lens blur radius: 2		54	# selecting a random lens blur radius to adjust the strength of the lens blur degrade		
4909 ppg - lens blur radius: 2			random lens blur radius = random randint(1, 3)		
6604 ppg - lens blur radius: 1					
5412 ppg long blue radius: 2			# opply long blue		
3415.prg - Tens blur radius: 3			# apply lens blur		
1127 ppg - lens blue radius, 2			result = tens_btur(img, radius=random_tens_btur_radius, components=4, exposure_gamma=		
2170 ppg - Tens Diur radius: 2					
2178.png - Tens Diur radius: 3		60	# construct full output file path		
64/3.png - Iens Diur radius: 1			<pre>output_file_path = os.path.join(output_folder_path, filename)</pre>		
5623.png - Iens blur radius: 1					
4643.png - Iens blur radius: 1			# save image in output folder		
4200.png - Iens blur radius: 2		64	cv2.imwrite(output file path, result)		
4327.png – lens blur radius: 1		65			
2788.png – Iens blur radius: 1			# add degradation strength to degradation output text file		
4005.png – lens blur radius: 3			print text to textfile(os nath ioi(textfile nath textfile name) filename + ' - ' +		
4678.png - lens blur radius: 3			print_coxt_to_coxtrict(os.path.join(coxtrict_path, textrict_name), ritename + + +		
4493.png - lens blur radius: 3			A print put in specia poull on these white herpering		
5511.png - lens blur radius: 1			* print out in console aswell so I see whats happening		
1430.png - lens blur radius: 3			print(filename, ' - lens blur radius;', random_lens_blur_radius)		
0118.png – lens blur radius: 2	Q	71			
4240.png - lens blur radius: 1			except:		
6431.png - lens blur radius: 1			print("An error occurred!")		

Made a python script to apply random lens blur strengths to that dataset



Realistic random lens blur strengths applied



Example images nomos8k\_sfw

### My ludvae200 degradation model applied, extended with logging strengths

(base) phips@phips-MS-7C02:~/Documents/datasets/RealSISR\_v2/ludvae200\$ p dvae200 inference.pv 0001 - noise: 8.110433577425216, temperature: 0.0453532838571727 0002 - noise: 5.242534348788979, temperature: 0.06313254501860299 0003 - noise: 4.485683419664755, temperature: 0.029743623846285885 0004 - noise: 3.5121359314009357, temperature: 0.07964461336727424 0005 - noise: 3.4054283598556143. temperature: 0.013917716859923058 0006 - noise: 8.178743952337207, temperature: 0.03887337754918066 0007 - noise: 4.780782845870358, temperature: 0.007267554720085912 0008 - noise: 4.314278615176603, temperature: 0.060950918613754956 0009 - noise: 6.9673430210726215. temperature: 0.06430152547528575 0010 - noise: 8.121725932762281, temperature: 0.09555013378273888 0011 - noise: 2.5198203874258196, temperature: 0.05902278291982885 0012 - noise: 1.4918474134407833, temperature: 0.012280633386160845 0013 - noise: 6.012990344102921, temperature: 0.07811950269323635 0014 - noise: 3.1688345034289966, temperature: 0.04007922313261565 0015 - noise: 3.9798155812564504, temperature: 0.00019470975853962404 0016 - noise: 5.464497987954985, temperature: 0.05767984769082346 0017 - noise: 1.9850817354277306, temperature: 0.09306347764634298 0018 - noise: 9.144466477857023, temperature: 0.06039212898722236 0019 - noise: 7.215344847956992, temperature: 0.08329094806775206 0020 - noise: 1.5265831001420915, temperature: 0.03195038021368224 0021 - noise: 7.6537427549593176, temperature: 0.05596887304876696 0022 - noise: 3.4430223699386286, temperature: 0.03478394951262279 0023 - noise: 4.664242111959391, temperature: 0.003953726548041415 0024 - noise: 2.2756737941468175, temperature: 0.0002692360819703477 0025 - noise: 6.705104807255619, temperature: 0.08148563000234021 0026 - noise: 1.3521305962241637, temperature: 0.04035584085989437 0027 - noise: 0.8857624371341832, temperature: 0.04771628567784623 0028 - noise: 2.5048029759469204, temperature: 0.03424615112040187 0029 - noise: 2.7926310175354265, temperature: 0.0817380150950508 0030 - noise: 7.630666452035127, temperature: 0.08960471604426883 0031 - noise: 0.19744112922010504, temperature: 0.08692316557213259 0032 - noise: 8.761271413885606, temperature: 0.0034463409694602157 0033 - noise: 7.857941278964794, temperature: 0.0492429793524396 0034 - noise: 6.926239619425778, temperature: 0.04905284323184958 0035 - noise: 6.689830276350404, temperature: 0.08165175838910603 0036 - noise: 0.8823727549754423, temperature: 0.05592537210379659 0037 - noise: 6.323444109609545, temperature: 0.008310071964400778 0038 - noise: 2.9036224211576513, temperature: 0.06303617595150299 0039 - noise: 3.042840320591451, temperature: 0.09779165063576001 0040 - noise: 2.97541740278516, temperature: 0.03700305435616285 0041 - noise: 6.596966876215424. temperature: 0.08561829543233004 0042 - noise: 6.9043442243882875. temperature: 0.06196013498320914 0043 - noise: 9.921821941721383, temperature: 0.06778350134175108 0044 - noise: 9.992100206241826. temperature: 0.05473364907003565 0045 - noise: 2.6425362827341017. temperature: 0.06064072760384429

1/1 <del>•</del> + [† □ … ts/datasets/RealSISR v2/ludvae200 Q ···· - |

1: phips@phips-MS-7C02: ~/Documents/datasets/RealSISR v2/ludvae200 -

H\_paths = util.get\_image\_paths(H\_path) idx, img in enumerate(H\_paths): img\_name, ext = os.path.splitext(os.path.basename(img)) img\_H = util.imread\_uint(img, n\_channels=3) img\_hH = img\_H.copy() img\_H = util.uint2tensor4(img\_H).to(device) img\_hH = util.uint2tensor4(img\_hH).to(device) noise\_strength = uniform(0,10) img\_hH = img\_hH + torch.randn\_like(img\_hH) \* noise\_strength / 255.0 label\_H = torch.zeros(1, 1, 1, 1).long().to(device)  $temperature_strength = uniform(0,0.10)$ img\_G = model.translate(img\_H, img\_hH, label\_H, temperature=temperature\_stren img\_G = util.tensor2uint(img\_G) util.imsave(img\_G, os.path.join(G\_path, img\_name + ext)) print\_text\_to\_textfile(os.path.join(textfile\_path, textfile\_name),img\_name + r(noise\_strength) + ', temperature: ' + str(temperature\_strength)) (img\_name + ' - noise: ' + str(noise\_strength) + ', temperature: ' + str

ludvae200\_inference.py

~/Documents/datasets/RealSISR v2/ludvae200



Ludvae200 applied



Realistic random lens blur strengths applied

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Scale and jpg compression applied



Scale and jpg compression applied



Scale and jpg compression re-applied, final Ir's





4xRealWebPhoto\_RGT\_60k

4xNearestNeighbor

WIP - Training and testing models to see if its a working approach



Improvement when increasing gt size from 128 (at 160k iters) to 256 (this is 200k)



Improvement again gt size from 256 to 384 (but 4 hours training for 1 checkpoint of 5k iters)



Validation results, 260k, ~109 hours of training https://slow.pics/s/1TRW2uBK



https://slow.pics/s/uCrGDwSe

# Thoughts

Tone down lens blur

Play around with degradations

#### degradr

Python library for realistically degrading images.

A blog post explaining the theory behind it a bit more can be found here.

The Demo.py file provides an example usage of the library and should degrade the included test image if you set up everything correctly.

For building the Intel Integrated Performance Primitives Python wrapper, which is needed for demosaicing, please download the IPP libraries (or the whole oneAPI Base Toolkit). Then adapt the additional library and include directories of the Visual Studio project to point to the targeted python version and compile as a Release x64 library. Copy the PyIPP.pyd file somewhere into your pythonpath / adapt the pythonpath (more info in this issue thread: #2). When running into trouble, this guide might help which is what I used for creating the wrapper library. If building on Linux, you're unfortunately on your own, but it should absolutely be doable as well.

The set of matrices for conversions between the camera and sRGB color space was derived from the LibRaw library and does NOT fall under the license of this project.

A sample usage of the library can be found in the Test.py script, which applies all steps necessary for degrading a "perfect" image. Before that, you'll need to run the ZernikePSF.py and PrepKernels.py script to prepare the convolution kernels. The applied steps are as follows (assuming the image is already in the camera color space):

- 1. Convert the input image to the assumed camera color space if needed.
- 2. Convolve by random blur kernel. (a combination of defocus blur, gaussian blur, PSFs generated from Zernike polynomials to model the lens aberrations, chromatic aberration)
- Color filter array (in practice applied directly before the demosaicing for simplicity, but this doesn't affect the output)

4. Poison noise

5. Gain

6. Read Noise

7. Quantization

8. Camera white balance

9. Demosaicing (3 different methods using the Intel Integrated Performance Primitives)

10. Color space transformation (from white balance corrected camera color space to sRGB) 11. JPEG Compression

### degradr



#### **Realistic Image Degradation**

2024-02-06

The qualitative performance of neural networks relies on how well the training input data matches the real data encountered during inference. Especially networks focusing on image denoising, deblurring or superresolution will heavily depend on small scale information on the pixel level. A typical pipeline for generating synthetic training data for those tasks is to start out with a high quality image, degrade it and use that one as the input during training.

In this blog post I want to introduce my pipeline for taking a perfectly fine image and making it ugly. BUT in a realistic way.

The following explanation probably leaves out a few steps, but I've tried to link to the Wikipedia page of all technical terms and the source code using pytorch is available on the "degradr" GitHub repository.

To start out imposing a short hafess it even hit your lang. It's perfect, as hive as showship abheration, as

#### The Theory

### Results

Here you can see an example of the library being tested on a small crop of an image of the <u>Heart Nebula</u> I took a while ago. (click to expand)



In summary, first the input is blurred by a random PSF which introduces blur and chromatic abberation. Then noise is added followed by the CFA and demosaicing. Note that the order of Noise and CFA doesn't matter for the implementation and this way it's easier to see the impact the CFA+Demosaic has on the noise distribution on a pixel scale. Lastly JPEG compression is applied further increasing the image degradation.

The python library is available here: https://github.com/nhauber99/degradr

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View statistics for this project via Libraries.io (2, or by using <u>our public</u> dataset on Google BigQuery (2

Degrade applied same dataset 5k ZernikeKernels but I removed demosaic step because of more complex dependency build setup



85k iters compact degradr

Degrade-non-demosaic result Compact



85k iters compact realwebphoto

Appendix: RealWebPhoto dataset creation with blur photo dataset - first try (v0)

-

RSBlur

Abstract Results Dataset Benchmark Bibtex Contact Coupe

# Realistic Blur Synthesis for Learning Image Deblurring

ECCV 2022

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Paper

Supple

Code

#### **Realistic Blur Synthesis for Learning Image Deblurring**

Jaesung Rim, Geonung Kim, Jungeon Kim, Junyong Lee, Seungyong Lee, Sunghyun Cho



#### RSBlur.zip

13,358 pairs of real/synthetic blurred image and a corresponding GT image.

**RSBlur\_additional.zip** 8,821 additional images for learning based synthesis, additional synthetic images or etc.

Do not use it as additional real training images.

**RSBlur\_sharps** All of sharp image sequneces.

GoPro\_INTER\_ABME.zip Synthetic blur dataset using the GoPro and the ABME method.

**GoPro\_U.zip** Synthetic blur dataset using the GoPro and synthetic blur kernels.

Code Training and Evaluation code

RSBlur.zip Properties					
		Basic	Permissions	Open With	
	Name: Type: Size:	RSBlur.zip Archive (app 114.7 GB	olication/zip)		

Name:	RSBlur
Туре:	Folder (inode/directory)
Contents:	120'240 items, totalling 115.0 GB

### Counts not only Files but also Folders





### 26'721 Images, 94 GB

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real\_blur--0001-000022-real\_blur.png







real\_blur--0001-000025-real\_blur.png













































More manageable size wise to continue processing ~59 Takes

But upon inspection was lacking in diversity. There were cars and structures. But for example no people / humans.

So I started handpicking Takes to get diversity: People, Cars, Structures, Plants, different Lightnings, and so forth, but still reducing dataset size for processing. (Also mentioning, I could have taken just one image per take to have diversity of takes. But they have differences of motion blurs in each take (or object in motion), so leaving them as takes has value I think)

Handpicked Szenes:

Dynamic scenes so lots of changes between shots / single images and also static ones with only camera shaking. People in motion. Food. Text. Cars. Buildings. Fence. Streets. Walls. Sky. Bright Sunlight. Sunlight and Shadows. Plants. Water. Glass. New: Selection of around 61 scenes. 1'175 Images, gt is currently 4.5GB

I also selected 4 val images i will process in the same way (that are not used in the training dataset)

Now the image resolutions were fluctuating. Width 1918, 1917 (most) and 1916 and height 1199 (most), 1198 and 1197. These are some weird resolutions for doing a 4x scale paired dataset.

I normalized the dimensions to 1920x1200. (So Ir's after processing would be 480x300). Plus I also normalized the filenames to integers.





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File "/home/phips/Downloads/DM600\_LUDVAE/LUD-VAE/LUD\_VAE\_ntire20/models/networ k\_ludvae.py", line 192, in translate

File "/home/phips/Downloads/DM600\_LUDVAE/LUD-VAE/LUD\_VAE\_ntire20/models/networ k\_ludvae.py", line 164, in decode\_uncond

File "/home/phips/Downloads/DM600\_LUDVAE/LUD-VAE/LUD\_VAE\_ntire20/models/networ k\_ludvae.py", line 11, in draw\_gaussian\_diag\_samples

```
return torch.exp(logsigma) * eps + mu
```

torch.cuda.OutOfMemoryError: CUDA out of memory. Tried to allocate 1.10 GiB. GPU
0 has a total capacty of 11.76 GiB of which 246.88 MiB is free. Including non-P
yTorch memory, this process has 11.20 GiB memory in use. Of the allocated memory
11.07 GiB is allocated by PyTorch, and 5.48 MiB is reserved by PyTorch but unal
located. If reserved but unallocated memory is large try setting max\_split\_size\_
mb to avoid fragmentation. See documentation for Memory Management and PYTORCH\_
CUDA\_ALLOC\_CONF
(base) phips@phips-MS-7C02:~/Downloads/DM600\_LUDVAE/LUD-VAE/LUD\_VAE ntire20\$ pyt

hon ludvae200\_inference.py

Trying to apply my ludvae model, but running out of vram. I will need to mode the first half downsample step before this to not run out of vram

# Kim's Dataset Destroyer

| Kim2091 / helpful-scripts                                                |                                          |                                                                                                                                  | Q T                                                      | ype 🛽 to search 🛛 🕹 🕹 🛃 😂 🔩    |
|--------------------------------------------------------------------------|------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------|--------------------------------|
| Code 💿 Issues 👔 Pull requests                                            | 🕑 Actions 🖽 Projects 😲 Security          | ⊻ Insights                                                                                                                       |                                                          |                                |
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| ? main 🔹 🕂 🔍                                                             | 😂 Kim2091 Hacky pipeline fix 🚥           |                                                                                                                                  |                                                          | bfab8c4 - 3 days ago 🕥 History |
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| 🖿 Align Images                                                           |                                          |                                                                                                                                  |                                                          |                                |
| 盲 Dataset Destroyer                                                      |                                          |                                                                                                                                  |                                                          |                                |
| 🗋 README.md                                                              | 🗅 README.md                              |                                                                                                                                  | README.md                                                |                                |
| Config.ini                                                               | 🗅 config.ini                             | Update o                                                                                                                         |                                                          |                                |
| requirements.txt                                                         | 🗋 datasetDestroyer.py                    | Hacky pi                                                                                                                         |                                                          |                                |
| De-dupe Images                                                           | requirements.txt                         |                                                                                                                                  |                                                          |                                |
| <ul> <li>Extract Video Frames</li> <li>Find Misaligned Images</li> </ul> | README.md                                |                                                                                                                                  |                                                          |                                |
| <ul> <li>Hue Adjustment</li> <li>Image Tiling</li> </ul>                 |                                          | Written with the help of multiple AI assistants                                                                                  |                                                          |                                |
| Move Files                                                               |                                          | This script's main usage is to generate datasets for yo                                                                          | ur image models.                                         |                                |
| <ul> <li>Re-Save Images</li> <li>Verify Images</li> </ul>                |                                          | Note: Avoid running all degradations at once in comb<br>errors                                                                   | ination with ffmpeg options (mpeg, mpeg2, h264, hevc, vp | 9). It will likely cause       |
| LICENSE.md                                                               |                                          | Main factures                                                                                                                    |                                                          |                                |
| 🗅 README.md                                                              |                                          | Main leatures:                                                                                                                   |                                                          |                                |
|                                                                          |                                          | Adjustable degradations                                                                                                          |                                                          |                                |
|                                                                          |                                          | <ul> <li>Supports: Blur, noise, compression, scaling, quant</li> <li>Adjustable strengths and order for eveny degrade</li> </ul> | ization, and unsharp mask                                |                                |
|                                                                          |                                          | Adjustable strengths and order for every degrada     Video compression support through ffmpeg-pyth                               | on                                                       |                                |
|                                                                          |                                          | Progress bar                                                                                                                     |                                                          |                                |
|                                                                          |                                          | ► Supported filters:                                                                                                             |                                                          |                                |
|                                                                          |                                          | Usage:                                                                                                                           |                                                          |                                |
|                                                                          |                                          | <ul> <li>Download the script and the config.ini file</li> <li>Edit config.ini to your liking. Make sure to add file</li> </ul>   | paths! Comments within the file describe each function   |                                |

# Half downsample with scale only, textfile log to check variety, all sampling methods provided enabled, val images test

| 1/1 <del>-</del> + [† □-]@p                                                                                                                                                                      | hips-MS-7C02: ~/Documents/datasets/RealSISR Q                                                                                                                                                                                                                                                                                                                                    |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  | Save            |
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| 1: phips@phips-MS-7C02: ~/Docum                                                                                                                                                                  | ents/datasets/RealSISR 👻                                                                                                                                                                                                                                                                                                                                                         | 1 [mein]<br>2 input_folder = /home/                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            | ohips/Documents/datasets/RealSISR/RealSISR_val_lr_normalized                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |                 |
| (base) phips@phips-MS-7C02:~<br>loo% <br>(base) phips@phips-MS-7C02:~<br>loo% <br>(base) phips@phips-MS-7C02:~<br>loo% <br>(base) phips@phips-MS-7C02:~<br>loo% <br>(base) phips@phips-MS-7C02:~ | /Documents/datasets/RealSISR\$ python datasetDe<br>  4.00/4.00 [00:00<00:00, 21.<br>/Documents/datasets/RealSISR\$ python datasetDe<br>  4.00/4.00 [00:00<00:00, 22.<br>/Documents/datasets/RealSISR\$ python datasetDe<br>  4.00/4.00 [00:00<00:00, 24.<br>/Documents/datasets/RealSISR\$ python datasetDe<br>  4.00/4.00 [00:00<00:00, 8.7<br>/Documents/datasets/RealSISR\$ _ | stroyer.py<br>(0it/s]<br>(0it/s]<br>(5it/s]<br>stroyer.py<br>(6it/s]<br>stroyer.py<br>(6it/s]<br>stroyer.py<br>(6it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s]<br>(0it/s] | <pre>/phips/Documents/datasets/RealSISR/RealSISR_val_ir_normalized<br/>rocessed images (e.g., png, jpg)<br/>lossy format here, your images will be compressed again on to<br/>s to apply to images in specified order (e.g.,<br/>n,scale,quantization,unsharp_mask)<br/>e the order of degradations (True or False)<br/>e degradations applied onto the image. Useful for testing.</pre>                                                                                                                                                                                         | t_downsample0.5 |
|                                                                                                                                                                                                  | RealSISR_val_lr_normalized_downsampleha<br>~/Documents/datasets/RealSISR                                                                                                                                                                                                                                                                                                         | if.txt 12 print = Faise<br>13 # Wheter to print the                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |                 |
| <pre>3.png - scale: lanczos si<br/>2 1.png - scale: gauss size<br/>30.png - scale: linear siz<br/>4 2.png - scale: down_up sc<br/>scale2algorithm=cubic_cat</pre>                                | ze factor=0.5<br>factor=0.5<br>ale1factor=1.84 scale1algorithm=cubic_bspline<br>rom                                                                                                                                                                                                                                                                                              | scale2factor=0.27<br>scale2factor=0.27<br>16 textfile_path = /home.<br>17<br>18 # Blur settings<br>19 [MJur]<br>20 # List of available bi<br>21 algorithms = average.,<br>22 # Whether to choose a<br>23 randomize = True<br>24 # Range of values for<br>25 range = 1,16<br>26 #Adjusts the scaling<br>27 scale_factor = 0.25<br>28<br>29 # Noise settings<br>30 [noise]<br>31 # List of available n<br>32 algorithms = uniform,<br>33 # Whether to choose a<br>34 randomize = True<br>35 # Range of values for<br>36 range = 0.5                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              | applied_degradations.txt text file will be generated (or apport<br>/phips/Documents/datasets/RealSISR<br>lur algorithms (e.g., average,gaussian,anisotropic)<br>gaussian,anisotropic<br>random blur algorithm each time (True or False)<br>blur kernel size or standard deviation (e.g., 1,10)<br>of the blur range. For average and gaussian, this will add 1<br>bise algorithms (e.g., uniform,gaussian,color,gray,salt-and-p<br>gaussian,color,gray,salt-and-pepper<br>random noise algorithm each time (True or False)<br>noise intensity (e.g., 0,50) 11Do not go below 011 |                 |

Worked (not out of vram anymore). But visually inspecting the results, degradations seemed too strong. So i started adjusting the strength settings in my inference script for this model, with constant values, what is the strongest setting i think okay with this model. Then final setting would be uniform down to 0 for the model to learn.

| /1 <del>•</del> + [] <sup>*</sup> □ <sup>-</sup> ntire20 Q ···   - □ × op                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |                                                                                                                                                             | l<br>∼/Download                                                                            | udvae200_val_inference.py<br>s/DM600_LUDVAE/LUD-VAE/LUD_VAE_ntire20                                                                                |                                                                   |                                    |                               | ↑ Тор                              |
|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------|------------------------------------|-------------------------------|------------------------------------|
| /Downloads/DM600_LUDVAE/LUD-VAE/LUD_VAE_ntire20 🔻 🛛 🛛 🗙 🕢                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |                                                                                                                                                             | config.ini ×                                                                               | RealSISR_val_lr_nored_downsample0.5.txt $\times$                                                                                                   | applied_degradations.txt × 🔸                                      | ed_downsampleh                     | alf_ludvae200 - /ł            | 10 – 🗆 X                           |
| <pre>se) phips@phips-MS-7C02:~/Downloads/DM600_LUDVAE/LUD-VA<br/>UD_VAE_ntire20\$ python ludvae200_val_inference.py<br/>ise) phips@phips-MS-7C02:~/Downloads/DM600 LUDVAE/LUD-VA</pre>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              | from random import uniform                                                                                                                                  |                                                                                            |                                                                                                                                                    |                                                                   | 2R <b>R 00</b> ▶                   |                               |                                    |
| UD_VAE_ntire20\$ python ludvae200_val_inference.py 17<br>ise) phips@phips-MS-7C02:~/Downloads/DM600_LUDVAE/LUD-VA 18<br>UD_VAE_ntire20\$ python ludvae200_val_inference.py 19<br>ise) phips@phips-MS-7C02:~/Downloads/DM600_LUDVAE/LUD-VA 20<br>UD_VAE_ntire20\$ python ludvae200_val_inference.py 21<br>ise) phips@phips-MS-7C02:~/Downloads/DM600_LUDVAE/LUD-VA 22                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                | def main():<br>#<br># CHANGE THESE PARAMETE<br>#                                                                                                            |                                                                                            |                                                                                                                                                    |                                                                   | 0_<br>0_<br>noise10tem<br>p0.1.png | 0_<br>noise10tem<br>p0.2.png  | 0_<br>0_<br>noise10tem<br>p0.5.png |
| UD_VAE_ntire20\$ python ludvae200_val_inference.py 22<br>se) phips@phips-MS-7C02:~/Downloads/DM600_LUDVAE/LUD-VA 24<br>UD_VAE_ntire20\$ python ludvae200_val_inference.py 25<br>se) phips@phips-MS-7C02:-/Downloads/DM600_LUDVAE/LUD-VA 26<br>UD_VAE_ntire20\$ python ludvae200_val_inference.py 25<br>se) phips@phips-MS-7C02:-/Downloads/DM600_LUDVAE/LUD-VA 26<br>UD_VAE_ntire20\$ python ludvae200_val_inference.py 26<br>UD_VAE_ntire20 | <pre>H_path = '/home/phips/D<br/>H_path = '/home/phips/D<br/>G_path = '/home/phips/D<br/>H the folder path where<br/>model_pool = '/home/phi</pre>          | h<br>ocuments/datasets<br>th<br>ocuments/datasets<br>you placed the l<br>ps/Downloads/DM60 | /RealSISR/RealSISR_val_lr_normalized_down<br>/RealSISR/RealSISR_val_lr_normalized_down<br>udvae200 model file<br>0_LUDVAE/LUD_VAE_ntire20/translat | samplehalf/'<br>samplehalf_ludvae200/'<br>e/LUD_VAE_NTIRE/models' | 0_<br>noise10tem<br>p0.05.png      | 0_<br>noise10tem<br>p0.15.png | 0_<br>noise10tem<br>p0.png         |
| Se) phipsephips-MS-7C02: //Downloads/DM000_LUDVAE/LUD-VA 32<br>(JD_VAE_ntire20\$ python ludvae200_val_inference.py 31<br>(se) phipsephips-MS-7C02: //Downloads/DM600_LUDVAE/LUD-VA 32<br>(JD_VAE_ntire20\$ python ludvae200_val_inference.py 33<br>(JD_VAE_ntire20\$ python ludvae20      | <pre># Optional parameters w #  w ludvae model file nam model_name = 'ludvae200 # strengh parameters</pre>                                                  |                                                                                            |                                                                                                                                                    | value                                                             | 0_<br>noiseunifor<br>m0-10tem      | 1.png                         | 1_<br>noise0temp<br>0.png          |
| <pre>so_vhips@phips-MS-7C02:-/Downloads/DMG00_LUDVAE/LUD-VA 38<br/>UD_VAE_ntire20\$ python ludvae200_val_inference.py<br/>se) phips@phips-MS-7C02:-/Downloads/DMG00_LUDVAE/LUD-VA 39<br/>UD_VAE_ntire20\$ python ludvae200_val_inference.py 40<br/>se) phips@phips-MS-7C02:-/Downloads/DMG00_LUDVAE/LUD-VA<br/>UD_VAE_ntire20\$ python ludvae200_val_inference.py 41<br/>ise) phips@phips-MS-7C02:-/Downloads/DMG00_LUDVAE/LUD-VA</pre>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             | <pre># ivil put min value<br/>degradation_free as well as<br/>noise_level = 10 #unifo<br/>constant for tests<br/>temperature = 0.15 #(un<br/>noise_10</pre> |                                                                                            |                                                                                                                                                    |                                                                   | 1_<br>noise10tem<br>p0.1.png       | 1_<br>noise10tem<br>p0.2.png  | 1_<br>noise10tem<br>p0.5.png       |
| UD_VAE_ntire20\$ python ludvae200_val_inference.py 42<br>se) phips@phips-MS-7C02:-/Downloads/DM600_LUDVAE/LUD-VA 43<br>UD_VAE_ntire20\$ python ludvae200_val_inference.py 43<br>se) phips@phips-MS-7C02:-/Downloads/DM600_LUDVAE/LUD-VA 45<br>UD_VAE_ntire20\$ python ludvae200_val_inference.py 43<br>se) phips@phips-MS-7C02:-/Downloads/DM600_LUDVAE/LUD-VA 45<br>UD_VAE_ntir(base) phips@phips-MS-7C02:-/Downloads/DM600                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                                                                                                                                                             |                                                                                            |                                                                                                                                                    |                                                                   | 1_<br>noise10tem<br>p0.05.png      | 1_<br>noise10tem<br>p0.15.png | 1_<br>noise10tem<br>p0.png         |
| se) phips@phips-MS-7C02:~/Downloads/DM600_LUDVAE/LUD-VA 49<br>UD_VAE_ntire20\$                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      | #<br># Preparation                                                                                                                                          |                                                                                            |                                                                                                                                                    |                                                                   | 7551                               | <u>NS61</u>                   | Raz                                |
| 146 51                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              | # **************                                                                                                                                            |                                                                                            |                                                                                                                                                    |                                                                   | .png" selected (1.2                | MB), Free spa                 |                                    |



Input example (validation image)



Ludave200 inferred example, max degraded



Val images example degraded with adjusted values for my model (these are only 4 images, the random strength distribution will be way better on the training dataset)

Same thing for the Ir folder - downsample then Iudvae200



Adding jpg compression with 60-100, google search preview images are 71. This simulates a person downsizing and compressing low quality (noise and blurry) photos to the web.

| 0.png | compression: | jpeg | quality=60 |
|-------|--------------|------|------------|
| 1.png | compression: | jpeg | quality=84 |
| 3.png | compression: | jpeg | quality=69 |
| 2.png | compression: | jpeg | quality=81 |

| 1 415.png - compression: jpeg quality=84   |  |
|--------------------------------------------|--|
| 2 307.png - compression: jpeg quality=82   |  |
| 3 131.png - compression: jpeg quality=82   |  |
| 4 558.png - compression: jpeg quality=90   |  |
| 5 470.png - compression: jpeg quality=72   |  |
| 6 244.png - compression: jpeg quality=83   |  |
| 7 631.png - compression: jpeg quality=85   |  |
| 8 769.png - compression: jpeg quality=96   |  |
| 9 83.png - compression: jpeg quality=86    |  |
| 10 1088.png - compression: jpeg quality=76 |  |
| 11 505.png - compression: jpeg quality=99  |  |
| 12 754.png - compression: jpeg quality=97  |  |
| 13 1130.png - compression: jpeg quality=97 |  |
| 14 1162.png - compression: jpeg quality=76 |  |
| 15 32.png - compression: jpeg quality=69   |  |
| 16 1138.png - compression: jpeg quality=68 |  |
| 17 164.png - compression: jpeg quality=89  |  |
| 18 157.png - compression: jpeg quality=62  |  |
| 19 513.png - compression: jpeg quality=62  |  |
| 20 447.png - compression: jpeg quality=98  |  |
| 21 1030.png - compression: jpeg quality=87 |  |
| 22 228.png - compression: jpeg quality=78  |  |
| 23 907.png - compression: jpeg quality=90  |  |
| 24 104.png - compression: jpeg quality=96  |  |
| 25 1172.png - compression: jpeg quality=84 |  |
| 26 776.png - compression: jpeg quality=81  |  |
| 27 731.png - compression: jpeg quality=79  |  |
| 28 890.png - compression: jpeg quality=95  |  |
| 29 1124.png - compression: jpeg quality=75 |  |
| 30 630.png - compression: jpeg quality=71  |  |
| 31 587.png - compression: jpeg quality=80  |  |
| 32 9.png - compression: jpeg quality=79    |  |
| 33 361.png - compression: jpeg quality=93  |  |
| 34 523.png - compression: jpeg quality=92  |  |
| 35 1068.png - compression: jpeg quality=99 |  |
| 36 1167.png - compression: jpeg quality=62 |  |
| 37 265.png - compression: jpeg quality=93  |  |
| 38 398.png - compression: jpeg quality=88  |  |
| 39 1160.png - compression: jpeg quality=73 |  |
| 40 985.png - compression: jpeg quality=92  |  |
| 41 1063.png - compression: jpeg quality=87 |  |
| 42 101.png - compression: jpeg quality=78  |  |
| 43 723.png - compression: jpeg quality=84  |  |
| 44 313.png - compression: jpeg quality=90  |  |
| 45 114.png - compression: jpeg quality=79  |  |
| 46 418.png - compression: jpeg quality=77  |  |
| 47 900.png - compression: jpeg quality=98  |  |
|                                            |  |

Plain Text - Tab Width: 8 - Ln 1, Col 1 INS

### Same to Ir folder



Then again applying scale, and then jpg compression to the Ir images. This is how the final Ir's might look like (the val images)



Here all the degradation steps on the example of 0.png, which is an already blurry image so no realistic blur needs to be added:

- I. linear 0.5
- 2. ludvae200
- 3. jpg 60
- 4. down\_up scale1factor=1.99 scale1algorithm=cubic\_catrom scale2factor=0.25 scale2algorithm=gauss
- 5. jpg 85

2024-02-22 20:00:25.352 INFO: ----- neosr Pvtorch Version: 2.2.0.dev20230914+cu121 2024-02-22 20:00:35,285 INFO: Dataset [paired] 2024-02-22 20:00:35,285 INFO: Training statist Starting model: 4xRealSISR\_rgt\_s Number of train images: 1175 Dataset enlarge ratio: 5 Batch size per gpu: 12 World size (gpu number): 1 Required iters per epoch: 490 Total epochs: 1021; iters: 500000. 2024-02-22 20:00:35,285 INFO: Dataset [paired] 2024-02-22 20:00:35,286 INFO: Number of val in 2024-02-22 20:00:36,327 INFO: Network [rgt] is 2024-02-22 20:00:36,421 INFO: Network [unet] i 2024-02-22 20:00:38,597 INFO: Loading rgt mode [params]. 2024-02-22 20:00:38,748 INFO: Loss [HuberLoss] 2024-02-22 20:00:39,080 INFO: Loss [Perceptua] 2024-02-22 20:00:39,081 INFO: Loss [GANLoss] : 2024-02-22 20:00:39,081 INFO: Loss [colorloss] 2024-02-22 20:00:39,089 INFO: Model [default] is created. 2024-02-22 20:00:39,949 INFO: Using CUDA prefetch dataloader. 2024-02-22 20:00:39,949 INFO: AMP enabled. 2024-02-22 20:00:39,949 INFO: Start training from epoch: 0, iter: 0 2024-02-22 20:49:41,478 INFO: [epoch: 10] [iter: 5,000] [performance: 1.697 it/s] [lr:(7.143e-05)] [eta: 3 days, 8:34:57, data\_time: 3.5581e-03 l\_g\_pix: 3.1343e-03 l\_percep: 6.0649e+00 l\_g\_color: 9.3354e-04 l\_g\_gan: 8.8242e-02 l\_d\_real: 9.6620e-01 out\_d\_real: -4.4727e-01 l\_d\_fake: 5.6470e-01 out\_d\_fake: -3.1836e-01 2024-02-22 20:49:41,478 INFO: Saving models and training states. 2024-02-22 20:50:01,904 INFO: Validation val Best: 22.9585 @ 5000 iter # psnr: 22.9585 # ssim: 0.3594 Best: 0.3594 @ 5000 iter 2024-02-22 21:38:55,121 INFO: [epoch: 20] [iter: 10,000] [performance: 1.711 it/s] [lr:(1.429e-04)] [eta: 3

days, 8:05:11, data\_time: 2.0218e-04 l\_g\_pix: 1.1371e-03 l\_percep: 5.5915e+00 l\_g\_color: 2.2461e-04 l\_g\_gan: 6.8779e-02 l\_d\_real: 6.5932e-01 out\_d\_real: 7.2754e-02 l\_d\_fake: 7.0201e-01 out\_d\_fake: 1.4099e-02 2024-02-22 21:38:55,122 INFO: Saving models and training states. 2024-02-22 21:39:13,589 INFO: Validation val # psnr: 27.4585 Best: 27.4585 @ 10000 iter # sim: 0.5913 Best: 0.5913 @ 10000 iter

2024-02-22 22:28:03,629 INFO: [epoch: 30] [iter: 15,000] [performance: 1.707 it/s] [lr:(2.143e-04)] [eta: 3 days, 7:19:41, data\_time: 2.1109e-04 l\_g\_pix: 1.3216e-03 l\_percep: 5.0609e+00 l\_g\_color: 2.0179e-04 l\_g\_gan: 9.0105e-02 l\_d\_real: 5.7890e-01 out\_d\_real: 1.2422e+00 l\_d\_fake: 6.7330e-01 out\_d\_fake: -2.2949e-01 2024-02-22 22:28:03,630 INFO: Saving models and training states. 2024-02-22 22:28:02,132 INFO: Validation val



Trained 2 experiment models with it, compact for 40k and rgt\_s for 70k. Problem: Motion blur in dataset is too strong. Need another realistic blur dataset. Better: Find a method to degrade with realistic blur with adjustable strengths instead of using pre-blurred dataset I cannot adjust